**Log of contributions**

**Theory**  
Differential kinematic model - Mads  
Robot arm kinematics and DH parameters - Gunnar  
Motion planning strategies - Everyone  
Model of total robotic system - Mads  
**Code**  
MatLab robot arm kinematics - Gunnar  
Simulink simulating kinematic model - Mads  
MatLab simulated trajectory - Nora  
MatLab simulated trajectory w/ plastic - Mads  
ROS robot simulation - Elias, Gunnar  
**Presentations**  
Preliminary design review - Everyone  
Critical design review - DNS  
Final presentation - Everyone  
**Report** **writing**  
Introduction - Anna  
Design Process - Anna  
Sensor implementation - Nora  
Robot arm implementation - Gunnar  
Mobile robot implementation - Mads  
Motion planning implementation - Nora  
Modelling of robot kinematics implementation - Mads  
Modelling total robotic system - Mads  
Pursuing pieces of plastic experiment - Mads  
Conclusion - Anna, ?, Mads, ?